

Moon Sensor Station to support lunar PNT and science as part of Moonlight

Richard Swinden, P. Giordano, Javier Ventura-Traveset, L. Cacciapuoti,
J. Carpenter, E. Schoenemann, S. Bruni, W. Enderle, D. Gomez Otero

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MOONLIGHT CONTEXT

MOON STATION POTENTIAL BENEFITS

 Moonlight Lunar Communications & Navigation Services

 Science

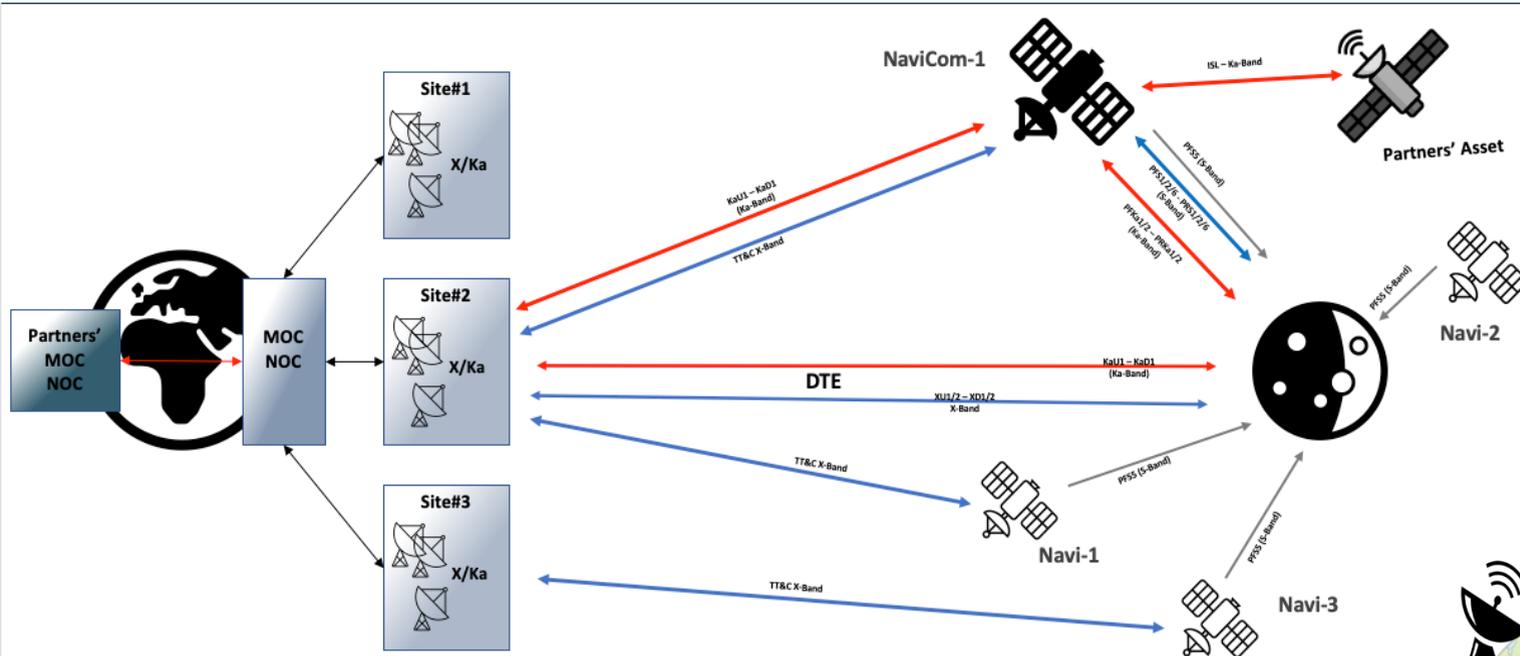
LUNAR ENVIRONMENT & CONSTRAINTS

MOON STATION FUNCTIONAL ANALYSIS

MOON STATION HIGH-LEVEL ARCHITECTURE

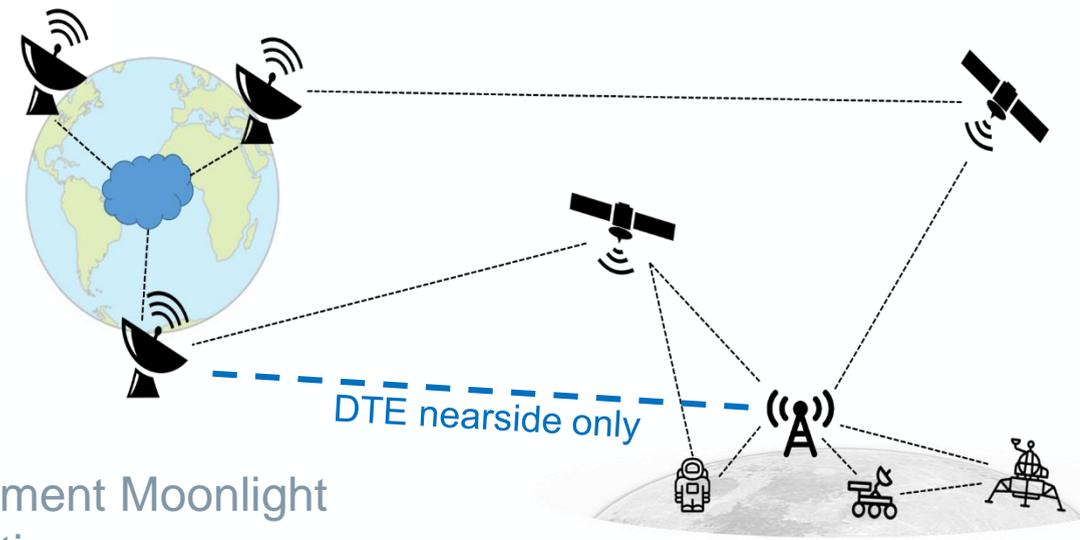
CONCLUSIONS & ROADMAP

MOONLIGHT CONTEXT



Links are named in-line with LunaNet spec

Initial Moonlight concept with 4 lunar orbiters and DTE links for ODTs

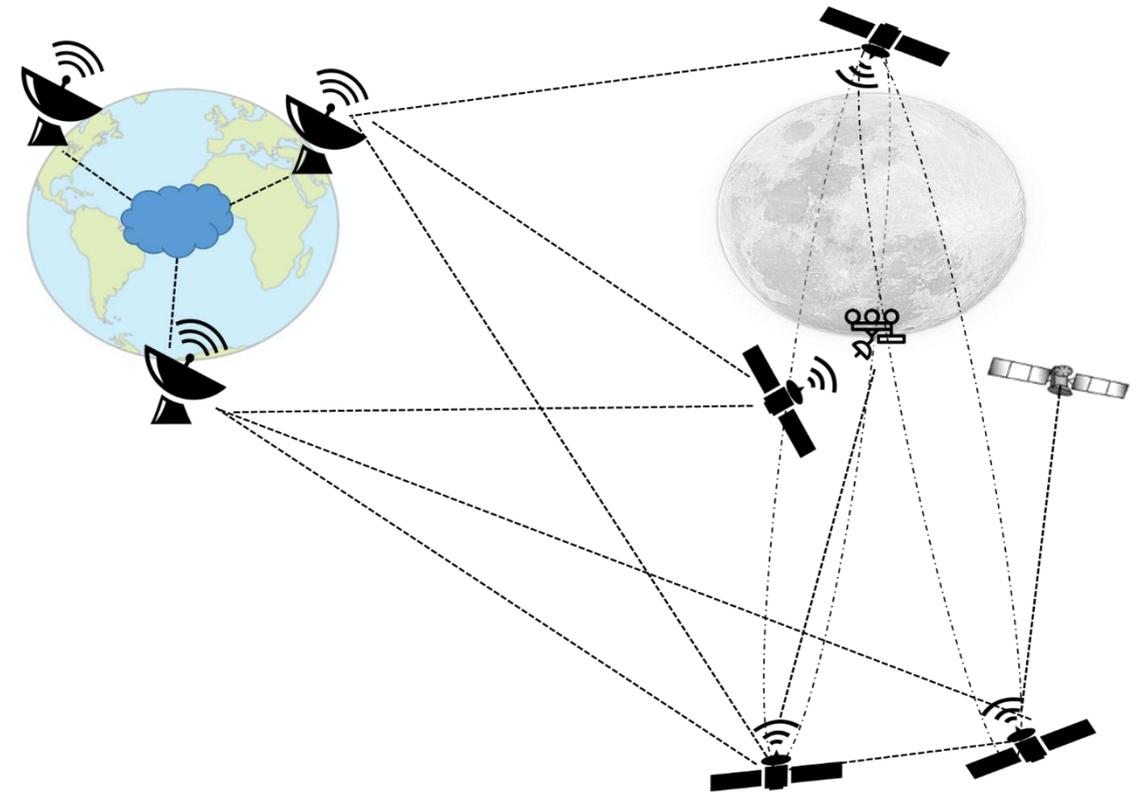


Potential to augment Moonlight with surface stations

1) Improved Orbit Determination & Time Synchronisation of LCNS satellites:

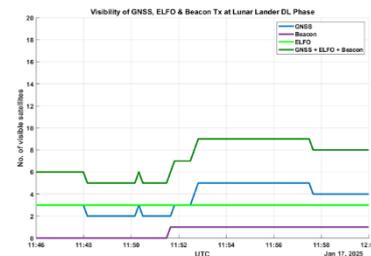
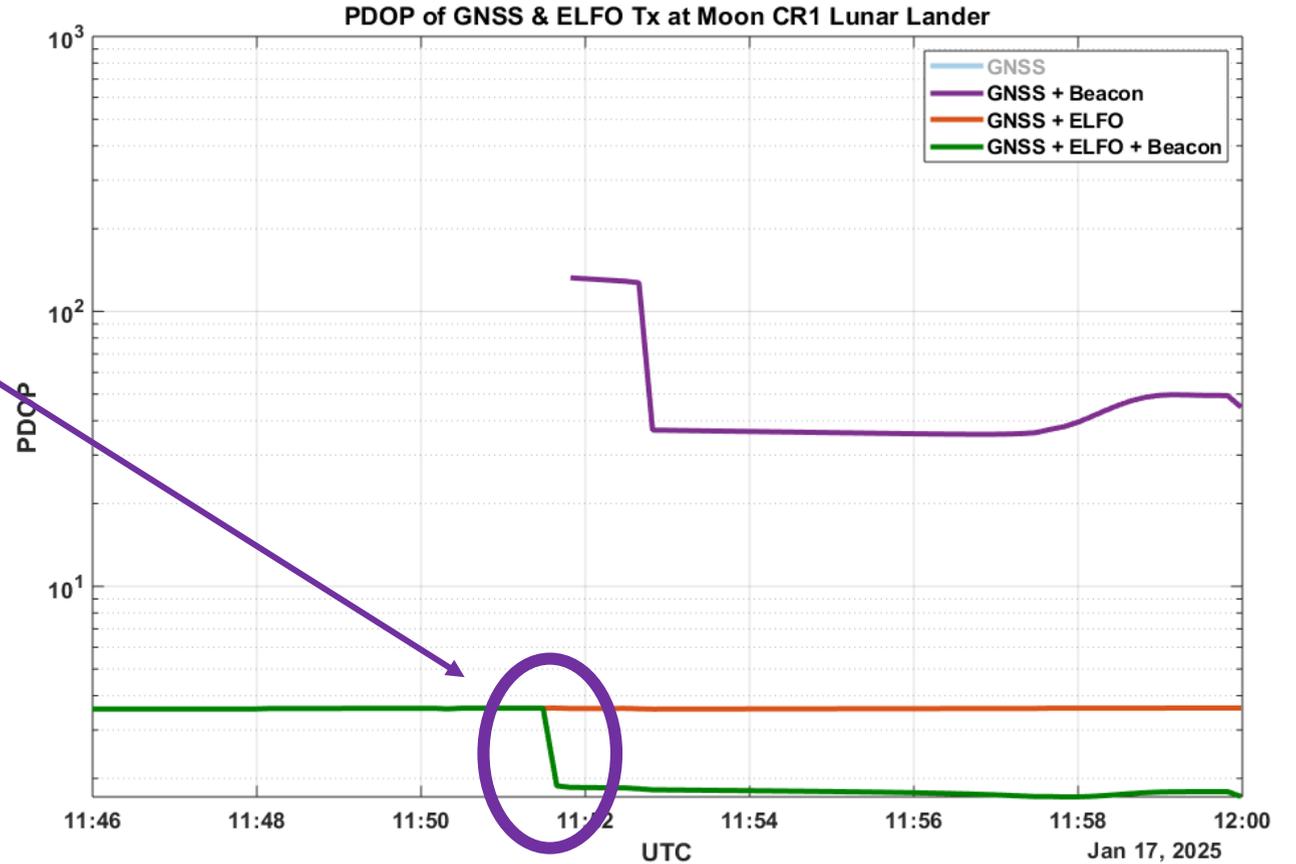
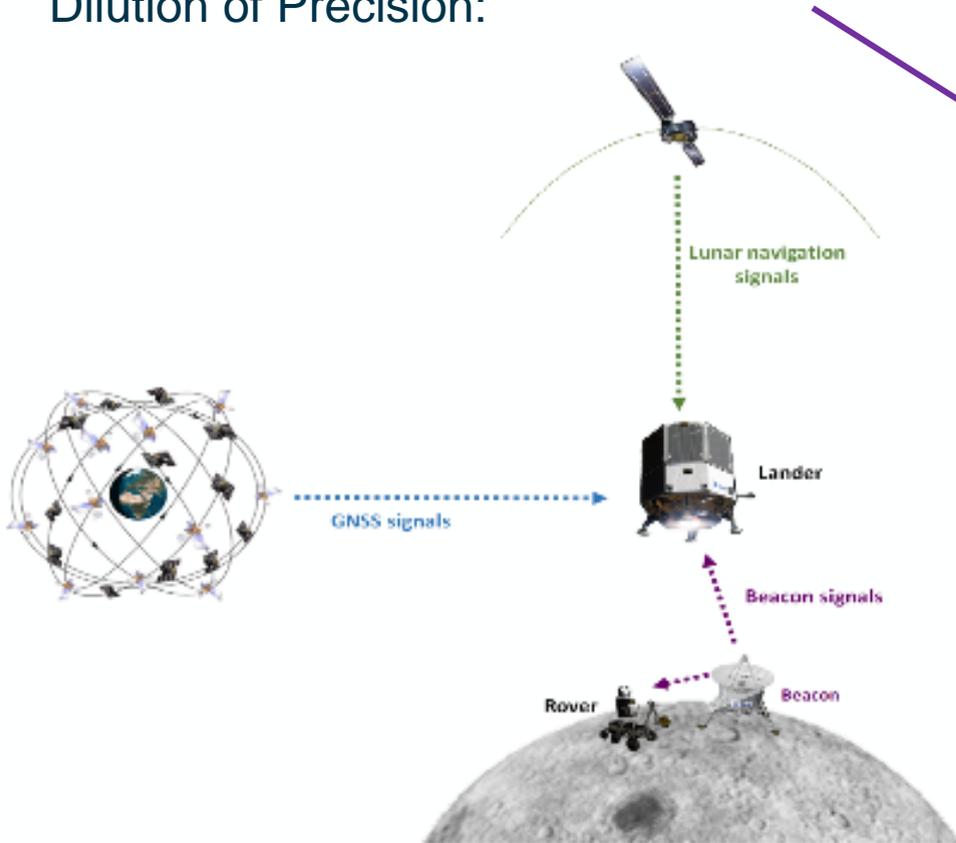
- Much improved geometry for ranging observations with LCNS satellites compared to the-Earth based observations, which all observe the orbits from approx. the same direction.

Better geometry => faster convergence
and better accuracies for orbit predictions



MOON STATION POTENTIAL BENEFITS - LCNS

3) **Additional ranging source** to improve geometry for user and reduce Dilution of Precision:



- Near-far effect for users close to beacon need to be mitigated
- Large curvature of moon limits the coverage of beacon signal for surface users

Laser ranging experiment to the Moon are routinely used to test Einstein’s Equivalence Principle.

The MoonLIGHT Pointing Actuator (MPAc) experiment is placing a 100 mm corner cube reflector on the Moon (@Rainer Gamma). The hardware will allow reaching mm-level accuracy in LLR measurements and improving General Relativity tests:

Science measurement / Precision test of violation of General Relativity	Apollo/Lunokhod * few cm accuracy	MoonLIGHTs ** mm
Parameterized Post-Newtonian (PPN) β	$ \beta - 1 < 1.1 \times 10^{-4}$	10^{-5}
Weak Equivalence Principle (WEP)	$ \Delta a/a < 1.4 \times 10^{-13}$	10^{-14}
Strong Equivalence Principle (SEP)	$ \eta < 4.4 \times 10^{-4}$	3×10^{-5}
Time Variation of Gravitational Constant	$ \dot{G}/G < 9 \times 10^{-13} \text{yr}^{-1}$	5×10^{-14}
Inverse Square Law (ISL) - Yukawa	$ \alpha < 3 \times 10^{-11}$	10^{-12}
Geodetic Precession	$ K_{gp} < 6.4 \times 10^{-3}$	6.4×10^{-4}

* Williams et al., PRL 93, 261101 (2004).

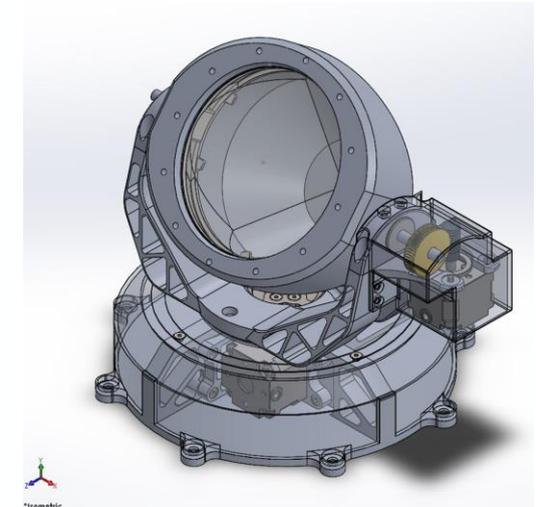
** Martini et al., Plan. & Space Sci. 74 (2012), 276-282.

** Ciocci et al., Adv. Space Res. 60 (2017), 1300-1306.

** Dell’Agnello et al., in Frascati Physics Series Vol. 66 (2018).



Rubino et al, Jul 2021



Additional CCRs deployed at dedicated sensor stations will help to further improve those limits.

Observation of quantum correlation strength in photonic states over:

Long distances

Large variations of the gravitational potential

A number of theoretical models attempt to predict how quantum correlations evolve in a curved space–time with contradicting results.

In the experiment, a pair of entangled photons is generated on the Earth. While one photon is detected locally, the other is sent towards the Moon sensor station and detected there.

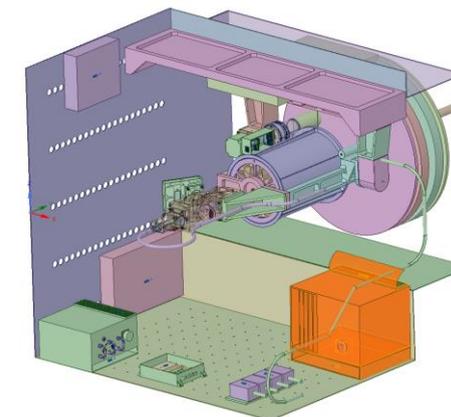
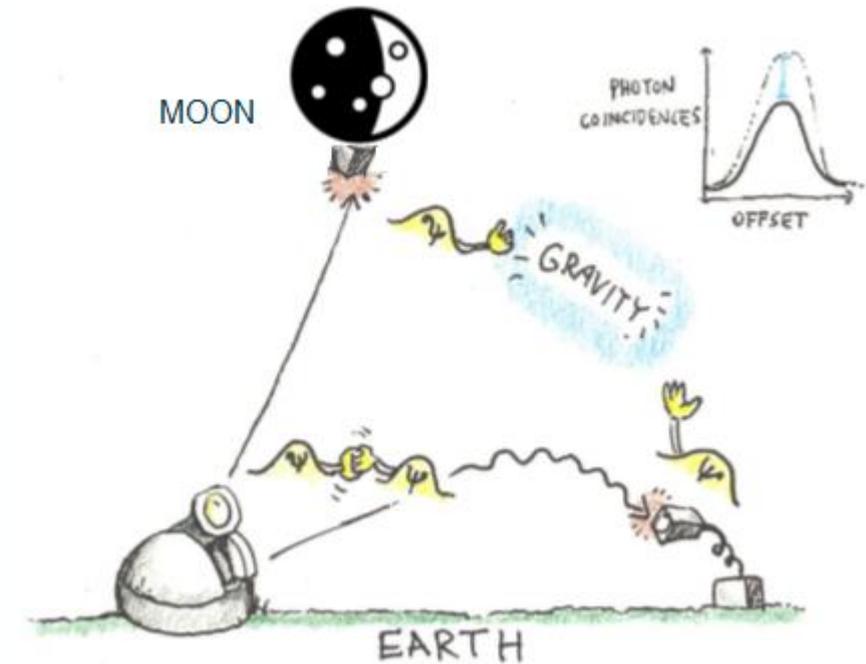
A sensor station equipped with a polarization-sensitive single-photon detection system can be used to test the boundaries between quantum mechanics and general relativity.

The experiment can additionally be used to:

Synchronize clocks at the sensor station to ground clocks

Test quantum cryptography and quantum key distribution schemes

Develop space-grade technology



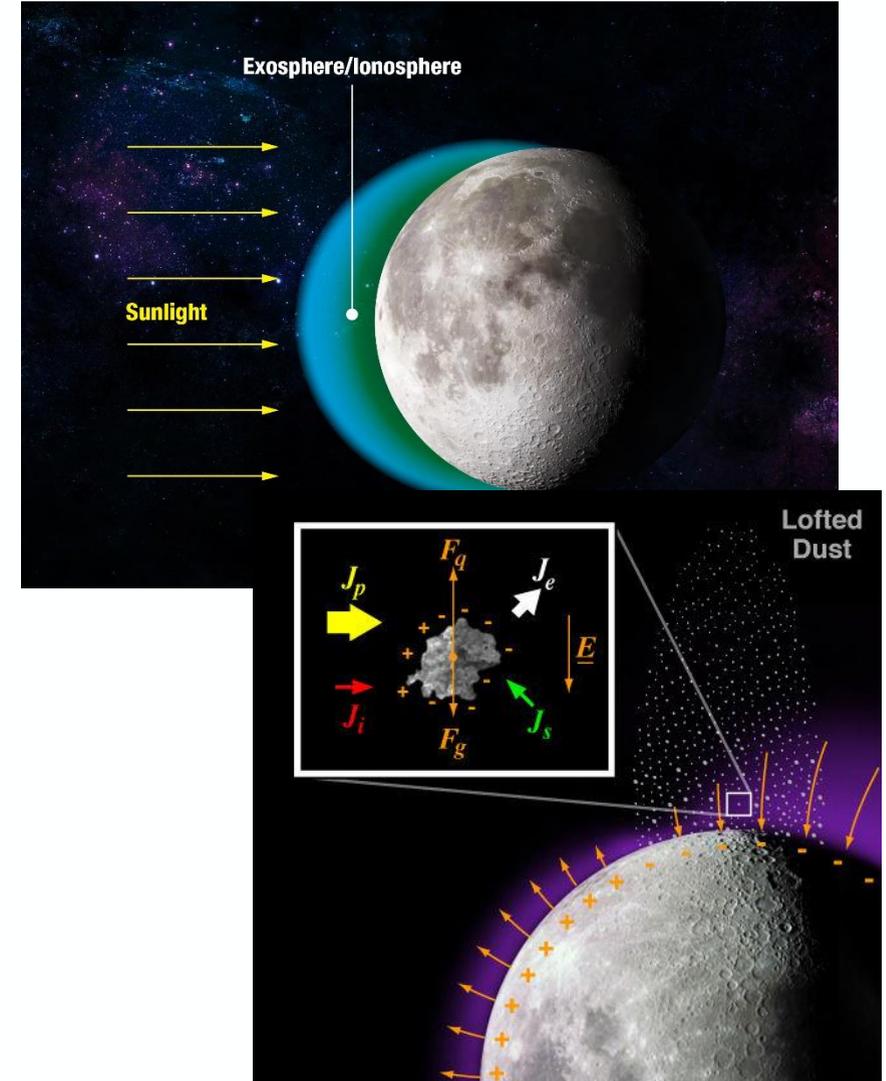
SpaceQuest mission with ISS

Thin lunar exosphere in combination with dust clouds supports a low density lunar ionosphere that is not well understood.

Ionosphere made of ionised dust instead of gas is new to planetary science. Unknown variation with time, moon phases and solar cycles.

Moon Station LCNS receivers could support this analysis observing the navigation signal delay similar to Ionospheric monitoring on earth with GNSS Sensor Stations

Some adaption needed due to single frequency navigation signal but aided by lack of tropospheric effects around the moon.

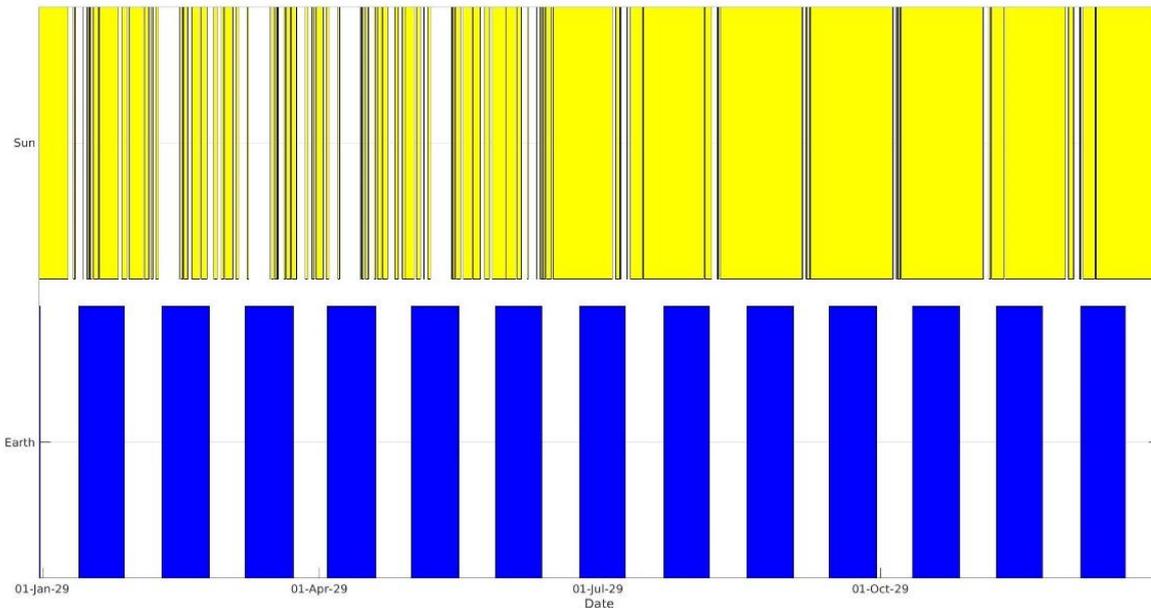


Credit: NASA 10

OTHER IDEAS FOR SCIENTIFIC BENEFITS?????

Lunar equatorial region has an approx. 14 earth day/night cycle but South Pole has areas of very high sun illumination

However, large variation in sun illumination (and earth visibility) depending on selected landing site, height above the surface and the mission timeframe (seasonal variations):

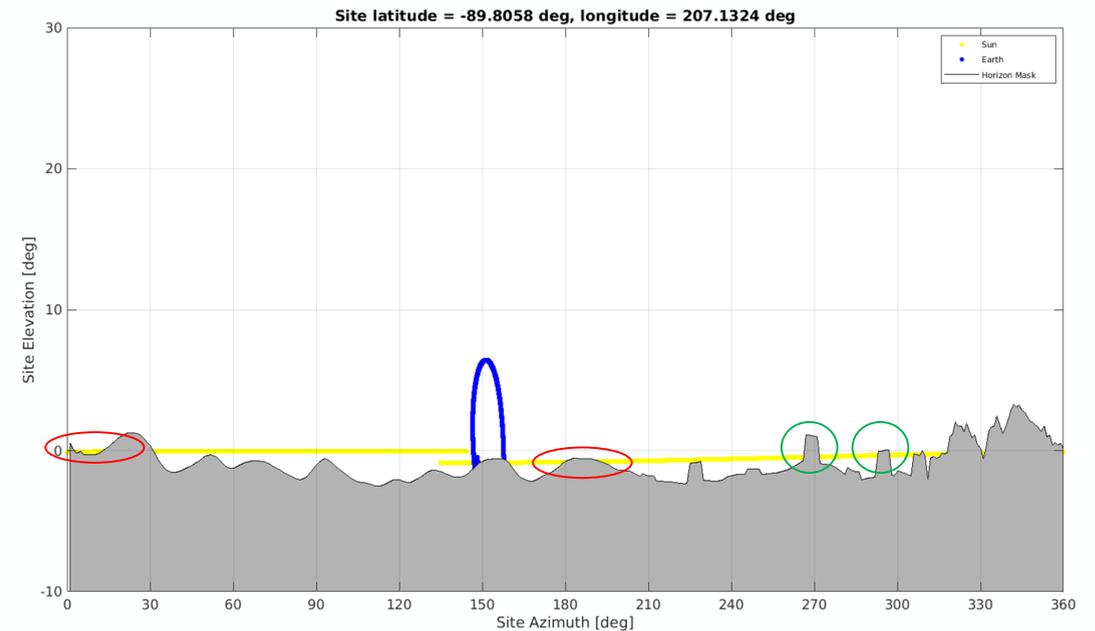


Shackleton crater rim, Sun and Earth visibility for 2029

Impacted by the local terrain mask:

Examples of unpredictable transients with Sun at edge of horizon marked in **Red**

Example full illumination blockages marked in **Green**

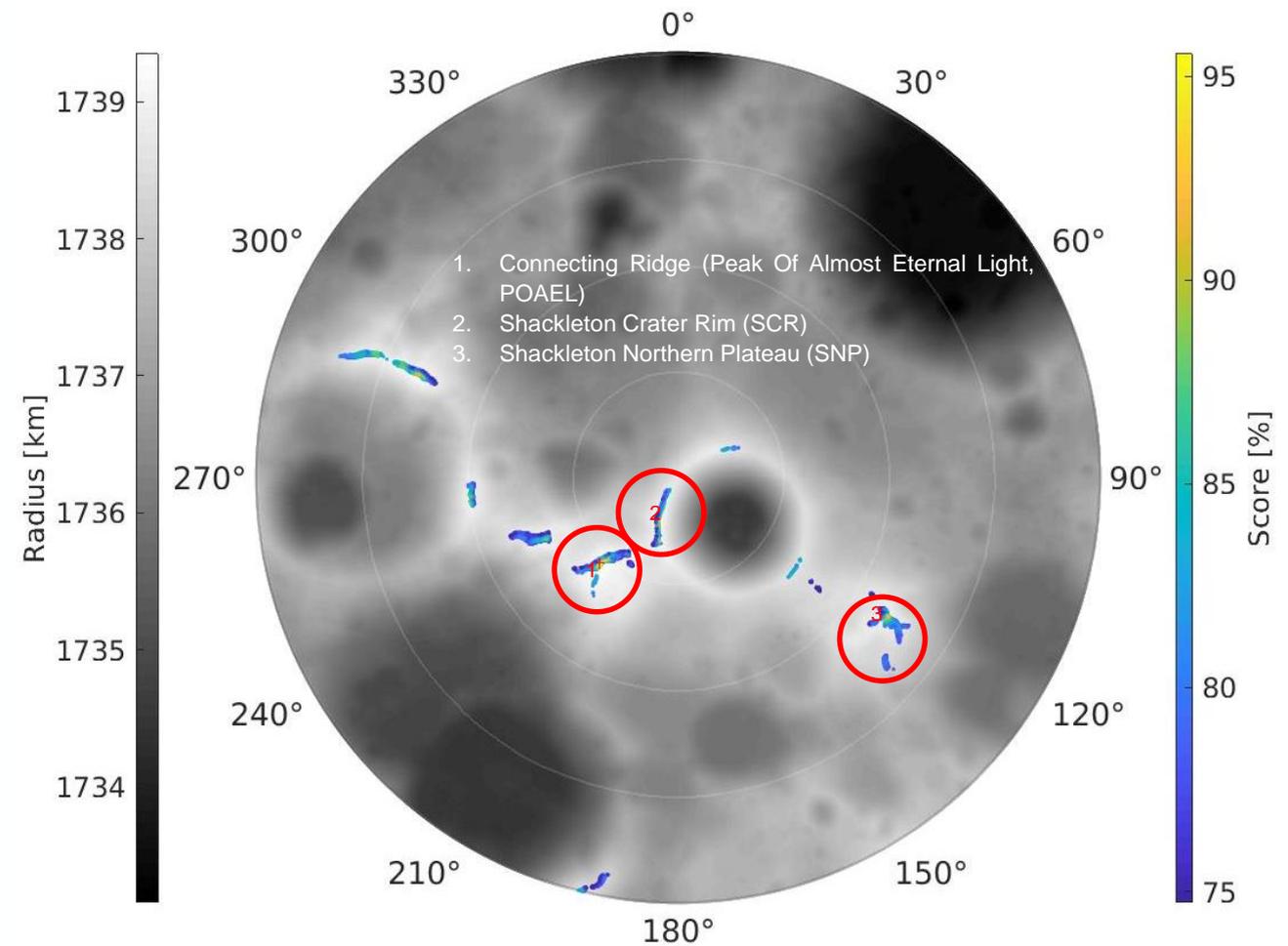


Shackleton crater rim, solar transient analysis

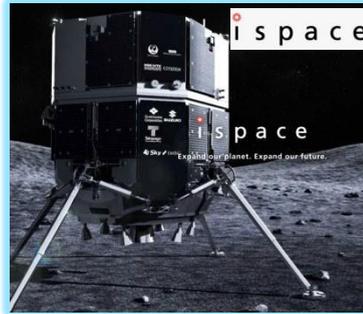
Analysis from ESA POLESTAR CDF

Potential South Pole landing areas can be defined according to the current lander capabilities and a sun illumination sizing case:

- >200m landing ellipse (Moonlight can help here!)
- AND average illumination is equal to or above 50 % over the simulated timeframe
- AND the longest continuous shadow period does not exceed 14 consecutive Earth days
- AND the slope does not exceed 15 degrees



Analysis from ESA POLESTAR CDF



Many different lander options in development (CLPS, LSAS, EL3) all with their own characteristics and capabilities.

Limited resources for payload in terms of:

- Mass (16-1700kg @ ~1M\$/kg)
- Volume
- Power/energy provision especially during lunar night
- Data link to Earth
- Dust/radiation protection
- Landing accuracy in terms of location and orientation (azimuth and elevation)

Additional constraints in terms:

1. mass distribution and payload units placement
2. heat exchanged with lander => units that need tight temperature control such as atomic clocks means large radiators and powerful heaters to manage extreme hot and cold cases.
3. distance from surface

In order to realise the potential benefits:

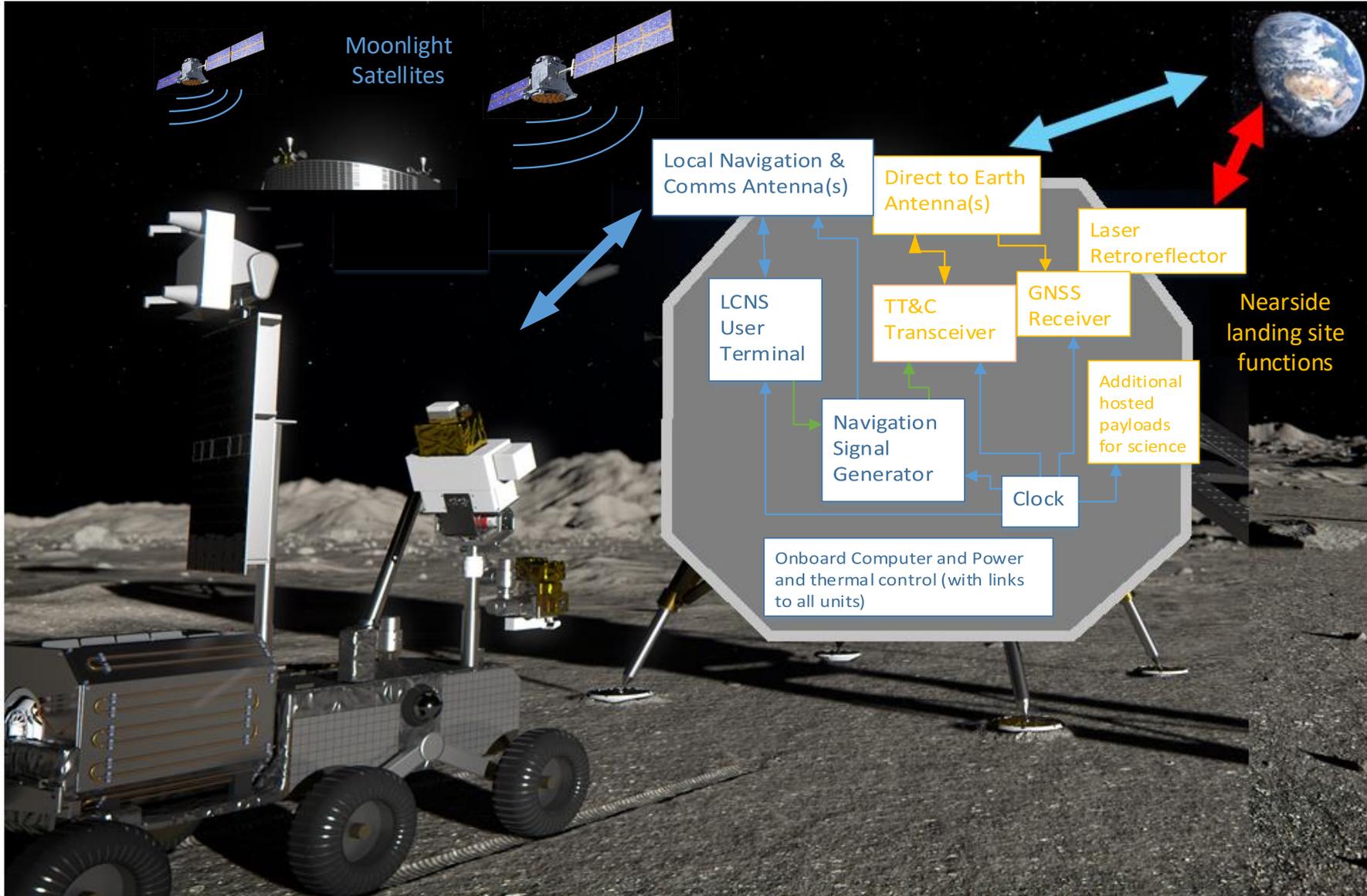
Core Functions:

- Perform ranging/doppler/time synchronisation with LCNS system
- Generate a navigation signal that augments or complements the LCNS satellite one-way signals (additional source and/or corrections to satellites signals)
- Receive and monitor the LCNS satellite navigation signals
- Exchange data with Earth (via TT&C DTE link or LCNS comms User Terminal)

Additionally for near-side stations:

- Perform ranging/doppler with Earth using multiple techniques: PN ranging, LRR, VLBI, SBI, GNSS
- Host additional units such as single photon detector for quantum experiments

MOON STATION HIGH-LEVEL ARCHITECTURE



Initial budget estimations:
 Mass: 30-65kg
 Power: 100-180W

Inc. all margins

Exact payload budgets dependent on potential reuse of lander capabilities for payload functions (TT&C, OBC, PSU etc)

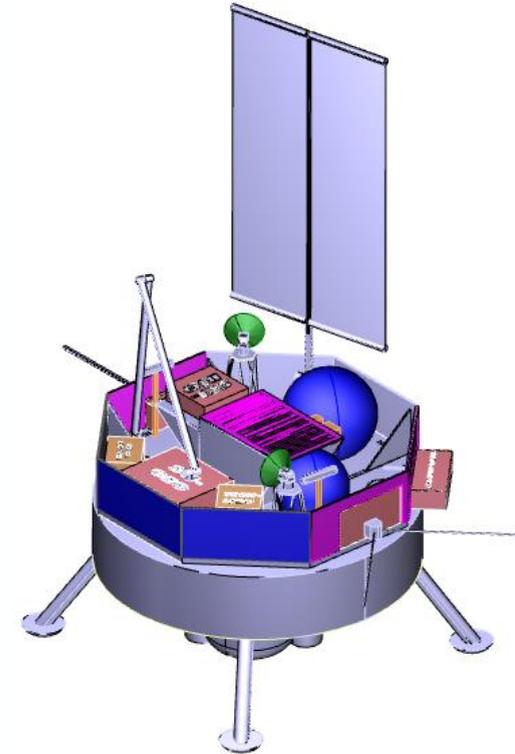
CONCLUSIONS & ROADMAP

Stations located on the lunar surface have the potential to greatly improve the Moonlight system performance as well as provide significant benefits to science

However, the lunar environment is harsh and the journey from earth to the landing site is arduous, which puts significant constraints on the station design and implementation especially for any long term operation on the surface.

An activity to study the potential and constraints in more detail and breadboard the needed critical functionalities is due to start shortly as part of the ESA NAVISP programme: **NAVISP ELEMENT 1-62: PNT MOON SURFACE BEACON DEMONSTRATOR**

The next step after this could be an in-space technology demonstrator or initial deployment with the Moon Station being a hosted payload aboard one of the lunar landers such as ESA's European Large Logistics Lander (EL3)



QUESTIONS?

Richard.Swinden@esa.int

