

# ESA's efforts towards a Combination On the Observation Level (COOL)

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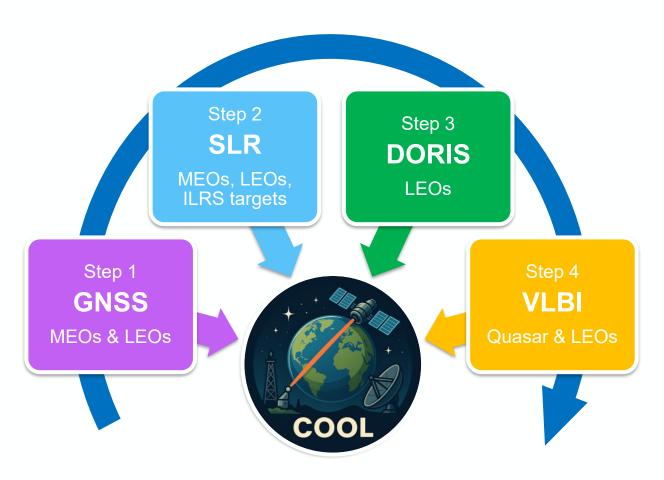
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### Combination On the Observation Level - COOL





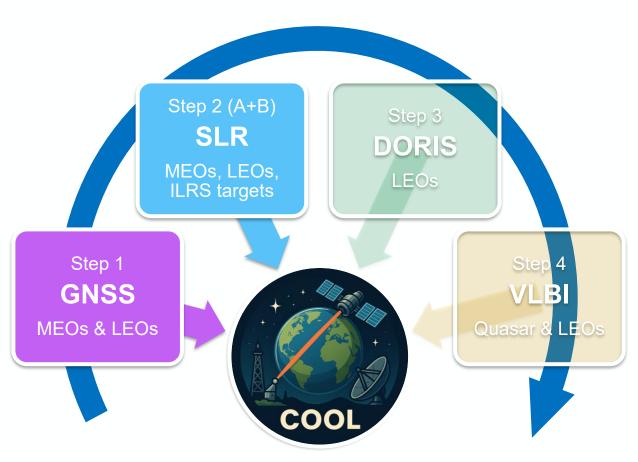
#### Main objectives:

- Combine all 4 geodetic techniques together in one single processing run
- Highlight the strengths of each technique
- Detect and reduce technique-specific systematics
- Exploit Normal Equation Stacking developed for Consolidated High-Accuracy Multi-GNSS Processing (CHAMP - 2024)
- Prepare the path, software and knowledge to achieve the Genesis mission goals

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### Combination On the Observation Level - COOL





#### Where we are now:

#### Step 1

#### GNSS + LEOs\*

- **LEOs** added to **Galileo** processing
- **LEOs** added to the **Multi-GNSS** processing

#### Step 2A

#### **SLR to Galileo and LEOs**

**SLR observations to Galileo and LEOs** added to the GNSS processing (previous step)

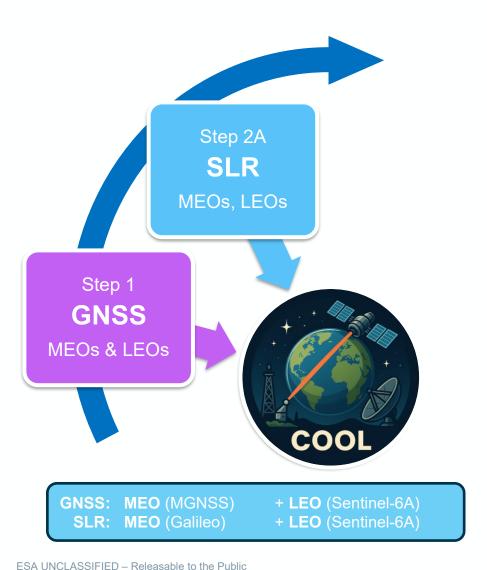
#### Step 2B

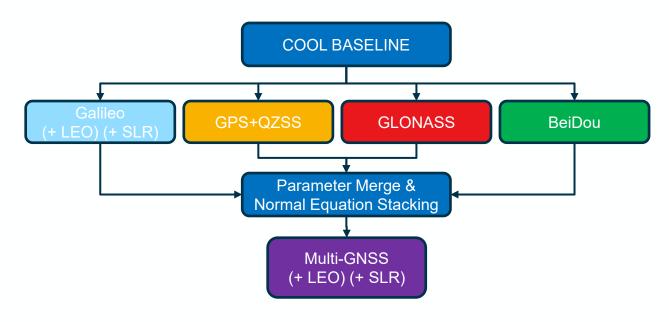
### **SLR to ILRS targets\*\***

- SLR observations to ILRS targets added to the GNSS+SLR processing (previous step)
- \* LEO = GNSS from Sentinel-6A (Galileo only obs.)
- \*\* SLR = SLR from GNSS and LEO satellites
- \*\* ILRS = SLR from ETALON, LARES & LAGEOS

### **COOL: GNSS & SLR (GNSS and LEO)**







#### **Observations selection**

At this step only SLR to GNSS and LEO satellites is included

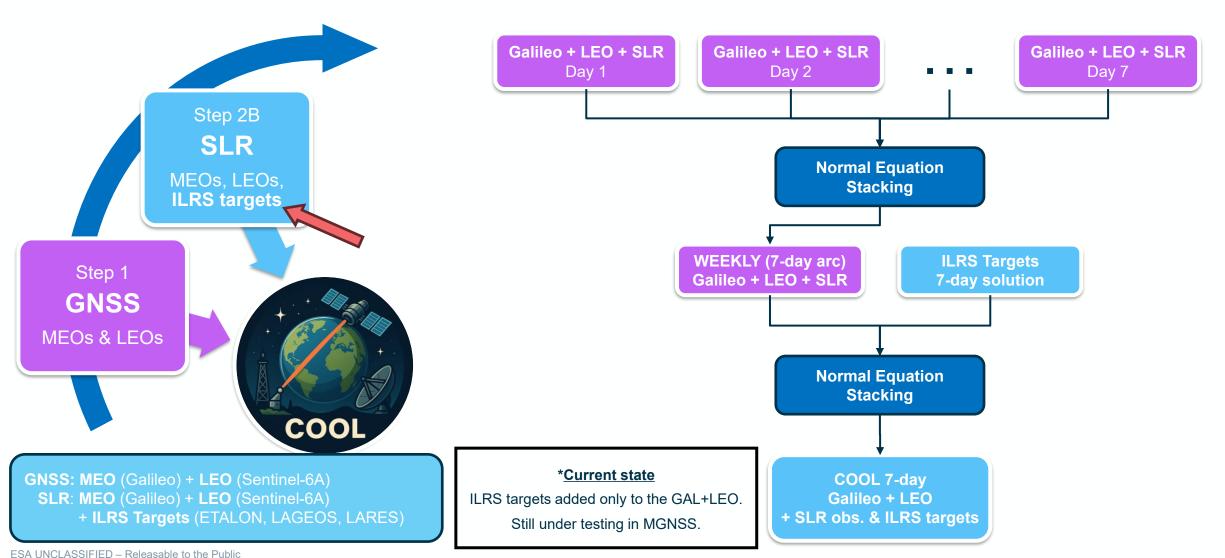
#### **Observations sampling**

- Standalone constellations (300s)
- MEO+LEO combinations (30s)

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### COOL: Galileo\* & SLR (including ILRS targets)





### Combination On the Observation Level - COOL



Solution Label	Description					
GAL	Galileo only (GNSS only)					
GAL-LEO	Galileo + LEO (GNSS only)					
GAL-LEO-SLR	Galileo + LEO + SLR - SLR: Galileo and LEO					
GAL-LEO-SLR-ILRS	Galileo + LEO + SLR + ILRS - SLR: Galileo and LEO - ILRS: LARES-2, 2xLAGEOS, 2xETALON					
MGNSS	All GNSS constellations (GNSS only)					
MGNSS-LEO	All GNSS + LEO (GNSS only)					
MGNSS-LEO-SLR	All GNSS + LEO +SLR - SLR: Galileo and LEO - ILRS targets not yet included					

<sup>\*</sup> First 200 days of 2024 were processed



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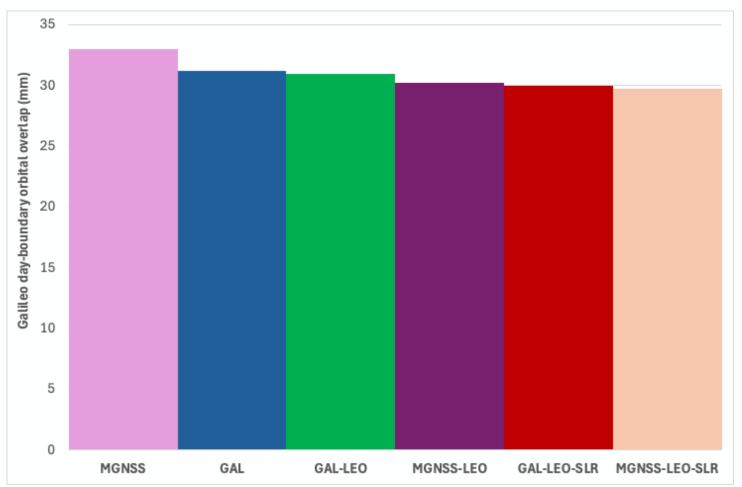






### **Satellite Orbit Overlaps for Galileo**





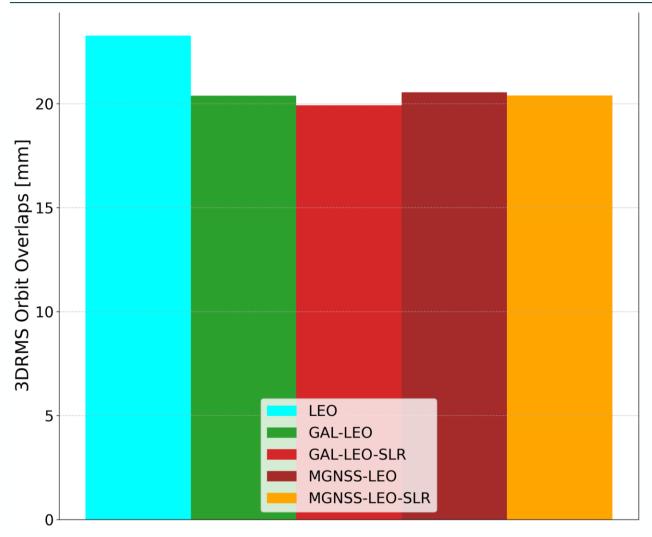
#### **Main findings:**

- Adding the LEO improves the GNSS orbit consistency, both Galileo and MGNSS
- Overall, the multi-satellite (GNSS, LEO) and multi-technique (GNSS & SLR) combination is superior in terms of Galileo orbit quality

<sup>\*</sup> See Backup slide for Galileo and LEO satellite specific results 7

### Satellite Orbit Overlaps for LEO: Sentinel-6A





\*LEO refers to ESA's Sentinel PPP solution, submitted to the Copernicus Regular Service Review

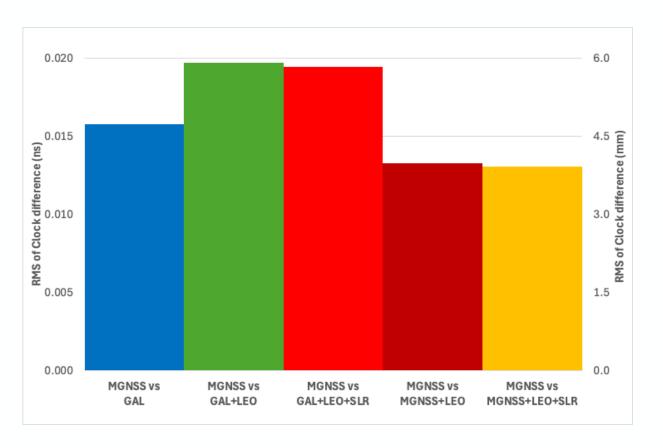
#### **Main findings:**

- Combining the LEO with Galileo considerably improves the LEO orbit consistency (20%)
- The addition of the SLR data further improves the LEO orbital consistency
- When combined with other constellations (both in case of GNSS-only and GNSS+SLR) the LEO orbit degrades marginally, but remains at the same level
- Overall, the multi-satellite (GNSS & LEO) and multi-technique (GNSS & SLR) combination is superior in terms of LEO orbit quality

<sup>\*</sup> See Backup slide for Galileo and LEO satellite specific results 8

### Clock comparison against Multi-GNSS solution





#### **Clock differences**

- Adding a single LEO receiver changes the results significantly, at the 35% level, which shows the power of including GNSS LEOs in GNSS solutions.
- SLR impact seems to be limited (after already including the LEO)
- We firmly believe that adding the GNSS LEO and the SLR observations improves the GNSS clocks
  - To be proven!

<sup>\*</sup> See Backup slide for Galileo satellite specific results

### **Global Earth Rotation Parameter estimates**



The following tables show the mean and standard deviation of the ERP estimates with respect to IERS EOP C04

- The Galileo and multi-GNSS solutions provide an almost unbiased solution for Length Of Day
- Incorporating the LEO into the solution primarily impacts the Polar estimates, leading to a substantial decrease in the mean but with a higher standard deviation
- SLR to Galileo and LEO do not have a significant impact on ERPs estimates
- The combination with the ILRS-targets slightly differs from the IERS solution. Cause still under investigation

Solution	Length of Day [µs]	X-Pole [mas]	Y-Pole [mas]
Galileo only	-0.02 ± 7.63	7.12 ± 13.96	15.34 ± 8.52
Galileo + LEO	0.92 ± 7.36	-0.11 ± 28.91	8.77 ± 18.24
Galileo + LEO + SLR	$0.89 \pm 5.73$	-0.81 ± 29.29	8.66 ± 18.48
Galileo + LEO + SLR + ILRS	0.65 ± 10.63	4.91 ± 15.11	15.37 ± 8.77
MGNSS	-0.65 ± 5.62	10.39 ± 8.73	12.03 ± 8.75
MGNSS + LEO + SLR	0.66 ± 5.73	6.75 ± 12.65	13.55 ± 6.88

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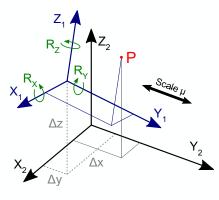


### Network ITRF alignment – Geocentre estimates



 ITRF alignment based on the common IGS20 and ILRS core stations, considering the origin of the ITRF2020u2023 as the real Geocentre. Up to 200 GNSS and 14 SLR stations overall

Helmert Transformation conditions						
Reference Case (default)	Free Translation Case					
No-Net-Translation Condition	Free Translation					
No-Net-Rotation Condition	No-Net-Rotation Condition					
Free scaling	Free scaling					



- The comparison between these cases shows how stable the origin (Geocentre) of the NNR solutions is
- The addition of LEO (S6A) and, additionally the SLR, brings the solutions closer to the ITRF origin

Cases (units are mm)	Galileo	Galileo + LEO	Galileo + SLR	Galileo + LEO + SLR	Galileo + SLR + ILRS	Galileo + LEO + SLR + ILRS	MGNSS	MGNSS + LEO + SLR
Geocentric offset 3D	13.06 ± 5.73	4.72 ± 1.84	8.63 ± 3.70	4.63 ± 1.83	6.82 ± 3.45	4.07 ± 2.05	6.13 ± 2.53	4.61 ± 2.01
X Y Z	0.08 ± 8.41 -1.82 ± 8.87 -2.12 ± 6.87	0.13 ± 2.24 -2.63 ± 2.00 -0.47 ± 3.08	0.01 ± 4.08 -1.01 ± 3.63 -5.01 ± 5.70	0.16 ± 2.22 -2.60 ± 2.06 -0.43 ± 2.95	0.26 ± 3.88 -0.81 ± 2.99 -4.18 ± 4.14	-0.14 ± 1.67 -1.84 ± 2.94 0.14 ± 2.54	1.07 ± 3.17 -0.20 ± 2.66 -2.61 ± 4.36	0.16 ± 2.25 -2.39 ± 2.05 -0.71 ± 3.14

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### **Conclusions**



- The addition of one GNSS receiver in LEO into a network of 200 ground-based receivers improves the solution:
  - Orbit overlaps are significantly enhanced, improving consistency and precision
  - Clock estimates show notable changes (likely improvements) pending further validation
  - The Polar Motion estimates within the Earth Rotation Parameters (ERP) show improved accuracy with respect to IERS, while their precision decreases
  - The Geocenter estimates is more consistent with the IERS and exhibit increased stability
- SLR observations to both Galileo and LEO further improve the solution
- The inclusion of ILRS targets is currently under investigation. First results show that the Geocentre estimates improve, whereas the ERPs estimates slightly degrade
- Besides being COOL, this work lays essential ground for the Genesis mission
- Only with hands-on implementation, missing elements can be uncovered

#### **Next steps:**

- Galileo Z-offset and ITRF scale validation are underway, incorporating estimated biases from SLR and ILRS
- DORIS and VLBI integration are next, with active development of VLBI-to-satellite functionality in our software

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# Thank You for your Attention!

Questions and feedback are welcome!





## **BACKUP** slides



































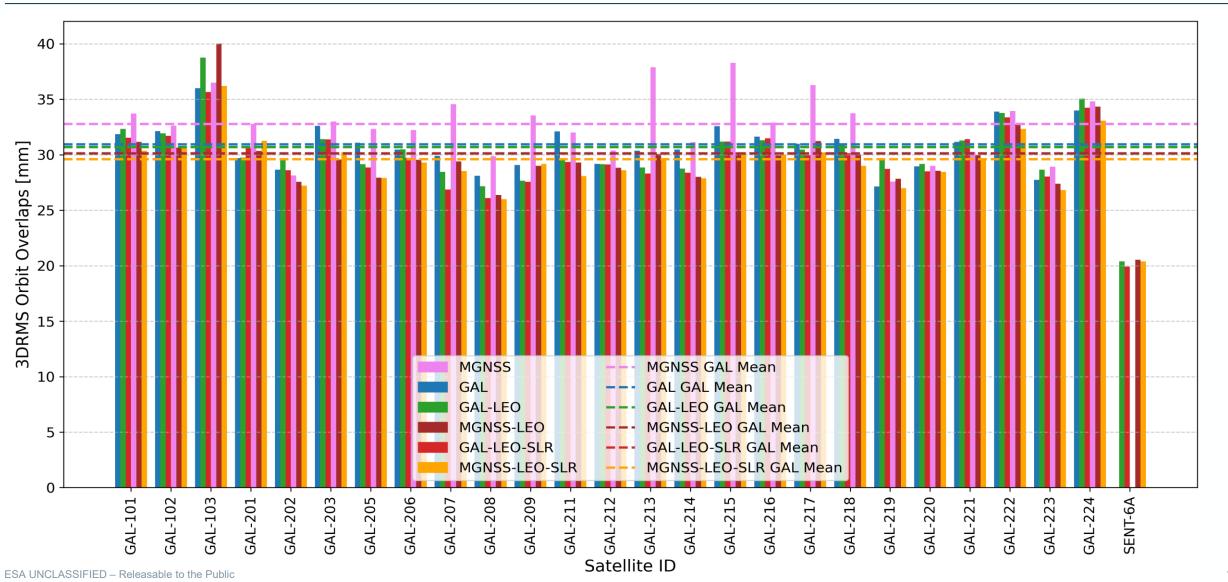






### Galileo satellite Orbit Overlaps: satellite specific results





### Galileo Clock comparison VS Multi-GNSS: satellite specific results



